Oscillation of Second Order nonlinear Neutral Difference Equations

S. Sindhuja¹, J. Daphy Louis Lovenia^{2*}, A. P. Lavanya³

S. Sindhuja¹, Assistant Professor, Department of Mathematics, Karpagam Institute of Technology, Coimbatore, India, <u>sindhusivaraj2211@gmail.com</u>

J. Daphy Louis Lovenia^{2*}, Professor, Department of Mathematics, Karunya Institute of Technology and Sciences, Corresponding Author, Coimbatore, India, <u>daphy@karunya.edu</u>

A.P. Lavanya³, Assistant Professor, Department of Mathematics, Sri Krishna college of Engineering and Technology, Coimbatore, India, <u>algebralavanya@gmail.com</u>

Article Info	Abstract
Page Number: 1095-1099 Publication Issue: Vol. 71 No. 4 (2022)	In this paper, we study the oscillatory behavior of secondorder nonlinear neutral difference equation of the form $\Delta^2(x(s) - ax(s - m)) = q(s)x(s - \sigma) + r(s)x(s + \tau)$
Article History Article Received: 25 March 2022 Revised: 30 April 2022	Examples are provided to illustrate the results. Keywords: Nonlinear neutral difference equation, oscillatory behavior.
Accepted: 15 June 2022 Publication: 19 August 2022	
1 T . 4 1 4	

1 Introduction

Consider the second order difference equation,

 $\Delta^2(x(s) - ax(s - m)) = q(s)x(s - \sigma) + r(s)x(s + \tau)$ (1.1)

where $s \in S(s_0), s_0$ is positive integer, *a* are real positive constant, $\{q_s\}, \{r_s\}$ are real sequences m, σ, τ are positive integers.

By the solution of (1.1), we mean real sequence $\{x(s)\}\$ is defined for $s \in S(s_0)$. A non-trivial solution $\{x(s)\}\$ is oscillatory if it is neither eventually positive nor eventually negative and non-oscillatory otherwise.

In the past few years, there has been an increasing interest in the study of oscillatory solutions of difference equations see [1 -5]. For example Grace S R [1],MałgorzataMigdaa and JanuszMigdab [3] have done an extensive work on this topic. The observative have motivated to study the oscillatory behavior of solutions of second order nonlinear neutraldifference equation

2 Main results

Theorem 2.1

Suppose $\sigma > \tau$, {q(s)} and {r(s)} where q(s) > 0, r(s) > 0 are non-increasing sequences, then

i)
$$\Delta^2 \mu(s) - r(s)\mu(s+\tau) \ge 0$$
 (2.1)

Vol. 71 No. 4 (2022) http://philstat.org.ph has no eventually nonnegative increasing solution,

ii)
$$\Delta^2 \mu(s) - q(s)\mu(s - \sigma) \ge 0$$
 (2.2)

has no eventually nonnegative decreasing solution,

iii)
$$\Delta^2 u(s) + \frac{q(s)}{a}u(s-\sigma+m) + \frac{r(s)}{a}u(s+\tau+m) < 0$$
 (2.3)

has no eventually nonnegative solution. Therefore all solutions of (1.1) oscillate.

Proof:Assume $\{x(s)\}$ is anonoscillatory solution for (1.1). With no loss of generality, we get $s_1 \in S(s_0)$ and $x(s-\theta) > 0$ for all $s \ge s_1$. Suppose z(s) = x(s) - ax(s-m). Then

$$\Delta^2 z(s) = q(s)(x(s-\sigma) + r(s)(x(s+\tau) > 0, s \ge s_1 \cdot (2.4))$$

where {*x*(*s*)} is non-oscillatory solution, according to (2.4), we claim $z(s) \ge 0$

By using the contradiction, assume that z(s) < 0 such that

$$0 < u(s) = -z(s) = -x(s) + ax(s - m) \le ax(s - m)$$

Then

.

$$x(s) \ge \frac{1}{a}u(s+m) \ s \ge s_2$$

By (1.1), we get
$$0 = \Delta^2 u(s) + q(s)(x(s-\sigma)) + r(s)(x(s+\tau)) \ge \Delta^2 u(s) + \frac{q(s)}{a}u(s-\sigma+m) + \frac{r(s)}{a}u(s+\tau+m)$$

which contradicts to (2.3)

Suppose,

$$\mu(s) = z(s) - \frac{a}{2} z_{s-m} (2.5)$$

$$\Delta^{2} \mu(s) = \Delta^{2} z(s) - \Delta^{2} \frac{a}{2} z_{s-m}$$

$$\Delta^{2} \mu(s) = q(s)(x(s-\sigma) + r(s)(x(s+\tau) - \frac{a}{2}(q(s-m)x(s-\sigma-m) + r(s-m)(x(s+\tau-m)))$$

$$\Delta^{2} \mu(s) = q(s)(x(s-\sigma)) + r(s)(x(s+\tau)) - \frac{a}{2}q(s-m)x(s-\sigma-m)$$

$$- \frac{a}{2}r(s-m)(x(s+\tau-m))$$
(2.6)

Vol. 71 No. 4 (2022) http://philstat.org.ph

$$\Delta^2 \mu(s) \ge q(s) [x(s-\sigma)] - a(q(s-m))(x(s-\sigma-m)) + r(s)(x(s+\tau)) - ar(s-m)(x(s+\tau-m))$$

$$\Delta^{2}\mu(s) \ge q(s)z(s-\sigma) + r(s)z(s+\tau) > 0$$
(2.7)

 $\mu(s) < 0,$

$$0 < v(s) = -\mu(s) = -z(s) + \frac{a}{2}z(s-m) \le \frac{a}{2}z(s-m)$$

Since

$$z(s) \le \frac{2}{a}v(s+m)$$

Using (2.7) we get,

$$0 \ge \Delta^2 v(s) + \frac{q(s)}{a} v(s - \sigma + m) + \frac{r(s)}{a} v(s + \tau + m)$$

This contradicts (2.3).

Case: (i)

Suppose $\Delta z(s) < 0$ for $s \ge s_3 \ge s_2$ such that $\Delta x(s) < 0$ for $s \ge s_2$,

By using the contradiction, let x(s) > 0, $\Delta x(s) > 0$, and $\Delta^2 x(s) > 0$ which gives $\lim_{s \to \infty} x(s) = \infty$

Since x(s) > 0, which implies z(s) > 0 but $\Delta z(s) < 0$, gives $\lim_{m \to \infty} z(m) = c < 0$.

By limits on (2.5), we get a contradiction. Using the monotonicity of $\{z(s)\}$ gives,

$$\mu_{s-\sigma} = z(s-\sigma) - \frac{a}{2} z(s-m-\sigma) \le z(s-\sigma)$$

By (2.7), we get

$$\Delta^2 \mu(s) \ge q(s)\mu(s-\sigma)$$

Therefore x(s) is nonnegative decreasing solution of equation (2.2), then it contradicts the proof.

Case: (ii)

Suppose $\Delta z(s) > 0$ for $s \ge s_4$. Two cases occur

Case:1

Vol. 71 No. 4 (2022) http://philstat.org.ph Suppose $\Delta x(s) < 0$ for $s \ge s_4$, the result is similar to case (i).

Case 2:

Suppose $\Delta x(s) > 0$ for $s \ge s_2$,

Since
$$\mu(s+\tau) = z(s+\tau) - \frac{a}{2}z(s-m+\tau) \le z(s+\tau)$$

By (2.7), we get

$$\Delta^2 \mu(s) \ge r(s)\mu(s+\tau)$$

which contradicts (2.1). The proof of the theorem is complete.

Theorem 2.2

Suppose $\sigma > m, \tau > m$

Let
$$\lim_{s \to \infty} \sup \sum_{t=s}^{s+\sigma-m} (s+\sigma-t-1)q > 1$$
(2.8)

$$\lim_{s \to \infty} \sup \sum_{t=s-\tau+m}^{s} (s-t+\tau-m+1)r > 1 \, (2.9)$$

and the inequality (2.3) has eventually negative increasing solution consequently, then all solutions of (1.1) oscillate.

Proof: According to the conditions (2.8) and (2.9), inequalities (2.1) has no eventually decreasing solution and (2.2) has no eventually increasing solution.

and (2.3) has eventually negative solution.

Therefore by theorem (2.1), the equation (1.1) is oscillatory.

3. Example

Example 1

Consider the equation

$$\Delta^{2}(x(s) - 2(3)^{m} x(s - m)) = -6(3)^{\sigma} x(s - \sigma) + 2(3)^{-\tau} x(s + \tau)$$
(3.1)

Here $a = 2(3)^m$, $q(s) = -6(3)^\sigma$, $r(s) = 2(3)^{-\tau}$

Theorem 2.2 is not satisfied for the condition (2.8). Then the condition (3.1)isnon-oscillatory solution for $\{x(s)\} = \{(3)^s\}$.

Example 2

Consider the equation

$$\Delta^{2}(x(s) - 4(2)^{m}x(s - m)) = -6(2)^{\sigma}x(s - \sigma) + 3(2)^{-\tau}x(s + \tau)$$
(3.2)

Here $a = 4(2)^m$, $q(s) = -6(2)^\sigma$, $r(s) = 3(2)^{-\tau}$

Theorem 2.2 is not satisfied for the condition (2.9). Then the condition (3.2) is non-oscillatory solution for $\{x(s)\} = \{(2)^s\}$.

References

- 1. Grace S R 1998 Oscillation of certain difference equations of mixed type J Math Anal Appl. 224 p 241–54.
- 2. Selvaraj B and Daphy Louis Lovenia J, Oscillation Behavior of fourth order neutral difference equations with variable coefficients, Far East Journal of Mathematical Sciences, 35(2), (2009), 225-231.
- 3. Lavanya A.P and Daphy Louis Lovenia J 2018 Positive solutions of a Fuzzy Nonlinear Difference Equations Tamsui Oxford Journal of Informational and Mathematical Sciences 32(2)(Aletheia University).
- Małgorzata Migdaa and Janusz Migdab, 2009 Oscillatory and asymptotic properties of solutions of even order neutral difference equations Journal of Difference Equations and Applications Vol. 15 Nos. 11–12 p 1077 – 84.
- S. Sindhuja, J. Daphy Louis Lovenia, A.P. Lavanya, and G.Jayabarathy2021 Application of certain Third-order Non-linear Neutral Difference Equations in Robotics Engineering International Conference on Robotics and Artificial Intelligence doi:10.1088/1742-6596/1831/1/012001.